

Formulas for Exams 1 and 2

1. Homogeneous equation $ay'' + by' + cy = 0$.

Three cases depending on the solutions r_1 and r_2 of the characteristic equation:

	solutions of the characteristic equation $ar^2 + br + c = 0$	fundamental solution of the equation $ay'' + by' + cy = 0$
1.	$r_1 \neq r_2$ real	$y_1 = e^{r_1x}$ and $y_2 = e^{r_2x}$
2.	$r_1 = r_2$ real	$y_1 = e^{r_1x}$ and $y_2 = xe^{r_1x}$
3.	r_1, r_2 complex $p \pm qi$	$y_1 = e^{px} \cos qx$ and $y_2 = e^{px} \sin qx$

Polar representation of complex numbers and Euler's formula:

$$z = x + iy = r \cos \theta + ir \sin \theta = r(\cos \theta + i \sin \theta) = r e^{i\theta}.$$

Finding n -values of the n -th root of a complex number $a = r(\cos(\theta) + i \sin(\theta)) = r e^{i\theta}$,

$$\sqrt[n]{a} = \sqrt[n]{r} e^{\frac{(\theta+2k\pi)i}{n}} \quad \text{for } k = 0, 1, \dots, n-1.$$

2. Non-homogeneous equation $ay'' + by' + cy = g(x)$.

The general solution is $y = y_h + y_p$ where y_h is the homogeneous and y_p the particular solution.

- (a) **Variation of Parameters.** If $y_h = c_1y_1 + c_2y_2$ is the solution of the homogeneous part of find the particular solution in the form $y_p = v_1y_1 + v_2y_2$. Find the unknown functions v_1 and v_2 from the equations

$$\begin{aligned} v_1'y_1 + v_2'y_2 &= 0 \\ av_1'y_1' + av_2'y_2' &= g(x) \end{aligned}$$

- (b) **Undetermined Coefficients.** Below $p_k(x)$ is a polynomial $a_kx^k + a_{k-1}x^{k-1} + \dots + a_0$ of degree k and p and q are real numbers.

Case 1 If $g(x) = p_k(x)e^{px}$, then $y_p = x^s(A_kx^k + A_{k-1}x^{k-1} + \dots + A_0)e^{px}$ where s is the number of times p appears on the list of zeros of the characteristic equation and A_0, \dots, A_k are undetermined coefficients.

Case 2 $g(x) = p_k(x)e^{px} \cos qx$ or $g(x) = p_k(x)e^{px} \sin qx$, then

$$y_p = x^s(A_kx^k + A_{k-1}x^{k-1} + \dots + A_0)e^{px} \cos qx + x^s(B_kx^k + B_{k-1}x^{k-1} + \dots + B_0)e^{px} \sin qx$$

where s is the number of times $p + iq$ appears on the list of zeros of the characteristic equation and A_0, \dots, A_k and B_0, \dots, B_k are undetermined coefficients.

If $g(x)$ is a sum of functions $g(x) = g_1(x) + g_2(x) + \dots + g_m(x)$ and each function $g_1(x), g_2(x), \dots, g_m(x)$ is a function described under two cases above, then the particular solution y_p is the sum of particular solutions

$$y_p = y_{p1} + y_{p2} + \dots + y_{pm}$$

where each solution $y_{pi}, i = 1, \dots, m$ is obtained as in Case 1 or 2 described above.

3. Applications.

- (a) Equation of the motion of a harmonic oscillator of mass m , the damping constant γ , spring constant k ($k = \frac{mg}{L}$ where L is the total elongation) and an external force $F(t)$ at time t .

$$mu'' + \gamma u' + ku = F(t).$$

If $\gamma = 0$, the oscillations are undamped. If $\gamma \neq 0$ and characteristic equation has real zeros, the motion is overdamped. If $\gamma \neq 0$ and characteristic equation has complex zeros, the oscillations are underdamped.

- (b) Equation of the charge of an electric circuit with the resistance R , the capacitance C and the inductance L containing a battery producing the voltage $E(t)$ at time t .

$$LQ'' + RQ' + \frac{1}{C}Q = E(t).$$

4. Derivatives and Integrals.

y	x^n	e^x	b^x	$\ln x$	$\log_b x$	$\sin x$	$\cos x$	$\sin^{-1} x$	$\tan^{-1} x$	$\sec^{-1} x$
y'	nx^{n-1}	e^x	$b^x \ln b$	$\frac{1}{x}$	$\frac{1}{x} \cdot \frac{1}{\ln b}$	$\cos x$	$-\sin x$	$\frac{1}{\sqrt{1-x^2}}$	$\frac{1}{1+x^2}$	$\frac{1}{x\sqrt{x^2-1}}$

y	x^n	e^x	b^x	$\frac{1}{x}$	$\sin x$	$\cos x$	$\frac{1}{\sqrt{1-x^2}}$	$\frac{1}{1+x^2}$
$\int y dx$	$\frac{1}{n+1}x^{n+1}$	e^x	$\frac{1}{\ln b} b^x$	$\ln x $	$-\cos x$	$\sin x$	$\sin^{-1} x$	$\tan^{-1} x$

- (a) Product rule: $y = f \cdot g \Rightarrow y' = f' \cdot g + g' \cdot f$

- (b) Quotient rule: $y = \frac{f}{g} \Rightarrow y' = \frac{f' \cdot g - g' \cdot f}{g^2}$ (c) Chain rule: $y = f(g(x)) \Rightarrow y' = f'(g(x)) \cdot g'(x)$

Integration by parts formula: $\int u dv = uv - \int v du$

- Separable Differential Equation:** $P(x)dx = Q(x)dy$. Integrate both sides.
- Linear Differential Equation:** $y' + P(x)y = Q(x)$. Integrating factor: $I(x) = e^{\int P(x)dx}$. After multiplying with $I(x)$, left side of the equation is equal to derivative of $I(x) \cdot y$.
- Homogeneous Differential Equation:** $y' = f(\frac{y}{x})$. Use substitution $u = \frac{y}{x}$ to reduce to a separable equation.
- Bernoulli's Differential Equation:** $y' + P(x)y = Q(x)y^n$. Use substitution $u = y^{1-n}$ to reduce to a linear equation. In this case $y = u^{1/(1-n)}$.
- Exact Differential Equation:** $Mdx + Ndy = 0$ if $M_y = N_x$. Find F as $\int Mdx$ and equate F_y with N . Solution is of the form $F = 0$.
- Autonomous Differential Equation:** $\frac{dy}{dt} = f(y)$. Can sketch the solutions without solving it. Find equilibrium solutions and check the sign of $f(y)$.
- Basic Differential Equation Models:**
 - Rate proportional to the size: $y' = ky$. Here k is a proportionality constant.
 - Total rate equal to the difference of rate in and rate out.
 - Total force equal to the sum of all acting forces.